Josiah Putman

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Education

Dartmouth College Class of 2020
Bachelor of Arts in Computer Science and Japanese, summa cum laude *Hanover, NH*
- Coursework focus: Robotics, Artificial intelligence, Deep learning, NLP. GPA 3.98 / 4.00

Experience

Google September 2020 – Current
Senior Software Engineer *Seattle, Washington*
- Lead developer of an LLM-based query targeting system used across Local Search Ads (LSA), accounting for over $1.3B in annual revenue. Utilized supervised fine-tuning and knowledge distillation to create a two-tower embedding model for low-latency serving. Managed cross-organization collaboration to integrate the system with various products in LSA, driving +$200M total growth in ARR for local, services, and travel ads.
- Fine-tuned SoTA Gemini models with RL to build a highly customizable query relevance classifier, generating an additional $120M in ARR for services ads while maintaining high user interaction rates.
- Built TPU-accelerated vector retrieval pipelines for classifying $O(10\text{B})$ queries in under 1 hour.

Urban Systems Lab - ClimateIQ May 2024 – May 2025
Machine Learning Fellow *Seattle, Washington*
- Designed and trained custom ConvLSTM architectures in JAX and TensorFlow for flood forecasting and atmospheric predictions in urban centers with less than 5% of the compute cost of standard physics-based simulations (event.newschool.edu/climateiq).
- Led research and exploration of different problem formulations, model architectures, and resource optimizations, enabling 100× training throughput and 90% reduction in RMSE.

UpTime Solutions September 2019 – August 2020
Machine Learning Engineer *Hanover, New Hampshire*
- Engineered ML models and data processing frameworks for bearing-fault detection in Keras and TensorFlow. Led development of Python API used for data aggregation, serving, and low-latency analysis pipelines.

Microsoft May 2019 – August 2019
Software Engineer Intern *Seattle, Washington*
- Developed cloud-scale WebSocket Server for MS Graph WebHook notifications in C#.

Dartmouth Robotics Lab June 2017 – August 2019
Undergraduate Researcher *Seattle, Washington*
- Research towards regression-based approximation algorithms for motion planning using Python, C/C++, Julia. Project lead for integration with Open Motion Planning Library.

Projects and Publications

PLRC* For Motion Planning | *IROS 2020* researchgate.net
- Researcher and lead developer (Julia, C++) for piecewise-linear regression complexes for approximately optimal motion planning.

Kataru | *YAML Based Dialogue Engine* kataru-lang.github.io
- Developed high-performance dialogue engine for simplifying writing dialogue for story-driven games in Rust, supporting JS/WASM targets and Unity. Built comprehensive developer tooling through a VS Code extension.

WASM Galaxy Simulation | *Physics Simulation on the Web* galaxy-sim.github.io
- Developed WASM-deployed Rust implementation of Barnes-Hut algorithm for scalable galaxy simulation (barnes-hut-rs).

Technical Skills

Languages: Rust, C/C++, C#, Python, Java, Go, Kotlin, SQL, GLSL, CSS
Technologies: CUDA, JAX, Keras, TensorFlow, PyTorch, ROS
Concepts: Machine Learning, Generative AI, Compilers, Data Analytics, Neural Networks, HPC, Game Development, Shaders, GPU